# Linear Sensor Indicator **K3HB-**

#### Linear Sensor Indicator for High-speed, Highprecision Measurement and Discrimination

- · Easy recognition of judgement results using color display that can be switched between red and green. \*
- · Equipped with a position meter that represents measured amounts and relative positions.
- · Develop a variety of measurement and discrimination applications using external event inputs.
- · Series expanded to include DeviceNet models.
- · Short body with depth of only 95 mm (from behind the front panel), or 97 mm for DeviceNet models.
- UL certification approval (Certification Mark License).
- · CE Marking conformance by third party assessment body.
- Water-resistant enclosure conforms to NEMA 4X (equivalent to IP66). \*Visual confirmation of judgement results is not supported on models that do not
- have an output or models that do not support DeviceNet. You can change the display color by setting it, but you cannot switch it based on the judgement results.

Refer to Safety Precautions for All Digital Panel Meters.

## Model Number Structure

## Model Number Legend

Base Units and Optional Boards can be ordered individually or as sets. **Base Units** 

- 1. Input Sensor Code SD: DC Process input
- 5. Supply Voltage 100-240 VAC: 100 to 240 VAC 24 VAC/VDC: 24 VAC/VDC

### **Optional Board**

#### Sensor Power Supply/Output Boards

K33-

**Relay/Transistor Output Boards** 

K34-∟

#### **Event Input Boards**



Note: The following combinations are not possible.

- Communications (FLK□A) + DeviceNet (DRT)
- Communications (FLK A) + BCD output (BCD)
- Linear current/voltage (L
  A) + DeviceNet (DRT)

### **Base Units with Optional Boards**

- 2. Sensor Power Supply/Output Type Code None: None

  - None: None CPA: Relay output (PASS: SPDT) + Sensor power supply (12 VDC +/-10%, 80 mA) (See note 1.) L1A: Linear current output (0 to 20 or 4 to 20 mA DC) + Sensor power supply (12 VDC +/-10%, 80 mA) (See note 2.) L2A: Linear voltage output (0 to 5, 1 to 5, or 0 to 10 VDC) + Sensor power supply (12 VDC +/-10%, 80 mA) (See note 2.) A: Sensor power supply (12 VDC +/-10%, 80 mA) FLK1A: Communications (RS-232C) + Sensor power supply (12 VDC +/-10%, 80 mA) (See note 2.) FLK3A: Communications (RS-485) + Sensor power supply (12 VDC +/-10%, 80 mA) (See note 2.)
- Note: 1. CPA can be combined with relay outputs only.
- Only one of the following can be used by each Digital Indicator: RS-232C/RS-485 communications, a linear output, or DeviceNet communications.

#### 3. Relay/Transistor Output Type Code

- None: None
- C1: Relay contact (H/L: SPDT each)
- C2: Relay contact (HH/H/LL/L: SPST-NO each) T1: Transistor (NPN open collector: HH/H/PASS/L/LL)
- T2: Transistor (PNP open collector: HH/H/PASS/L/LL)
- BCD \*: BCD output + transistor output (NPN open collector: HH/H/PASS/L/ ĽL)
- DRT: DeviceNet (See note 2.) \* A Special BCD Output Cable (sold separately) is required.
- 4. Event Input Type Code

#### None: None

- 1: 5 inputs (M3 terminal blocks), NPN open collector
- 2 \*: 8 inputs (10-pin MIL connector), NPN open collector
- 3: 5 inputs (M3 terminal blocks), PNP open collector
- 4 \*: 8 inputs (10-pin MIL connector), PNP open collector
- \* There is no bank selection for "None" and "DeviceNet" types of "Transistor Output Type Code".

safety standards, refer to your OMRON website.



For the most recent information on models that have been certified for

SP: 91°C €

## Accessories (Sold Separately)

K32-DICN: Special Cable (for event inputs, with 8-pin connector) K32-BCD: Special BCD Output Cable

### Watertight Cover

Model				
Y92A-49N				

### **Rubber Packing**

Model K32-P1

Note: Rubber packing is provided with the Controller.

## **Specifications**

## Ratings

Power supply voltage	)	100 to 240 VAC (50/60 Hz), 24 VAC/VDC, DeviceNet power supply: 24 VDC			
Allowable power sup	ply voltage range	85% to 110% of the rated power supply voltage, DeviceNet power supply: 11 to 25 VDC			
Power consumption (See note 1.)		100 to 240 V: 18 VA max. (max. load) 24 VAC/DC: 11 VA/7 W max. (max. load)			
Current consumption	1	DeviceNet power supply: 50 mA max. (24 VDC)			
Input		DC voltage/current			
A/D conversion method	od	Sequential comparison system			
External power suppl	У	12 VDC ±10%, 80 mA (models with external power supply only)			
Event inputs (See note 2.)		NPN open collector or no-voltage contact signal ON residual voltage: 3 V max. ON current at 0 $\Omega$ : 17 mA max. Max. applied voltage: 30 VDC max. OFF leakage current: 1.5 mA max.			
	Startup compensa- tion timer input	NPN open collector or no-voltage contact signal ON residual voltage: 2 V max.			
	Hold input	ON current at 0 $\Omega$ : 4 mA max. Max. applied voltage: 30 VDC max.			
	Reset input	OFF leakage current: 0.1 mA max.			
	Forced-zero input				
	Bank input				
Output ratings (de- pends on the model)	Relay output	250 VAC, 30 VDC, 5 A (resistive load) Mechanical life expectancy: 5,000,000 operations, Electrical life expectancy: 100,000 operations			
	Transistor output	Maximum load voltage: 24 VDC, Maximum load current: 50 mA, Leakage current: 100 $\mu$ A max.			
	Linear output	Linear output 0 to 20 mA DC, 4 to 20 mA DC: Load: 500 Ω max, Resolution: Approx. 10,000, Output error: ±0.5% FS Linear output 0 to 5 VDC, 1 to 5 VDC, 0 to 10 VDC: Load: 5 kΩ max, Resolution: Approx. 10,000, Output error: ±0.5% FS (1 V or less: ±0.15 V; no output for 0 V or less)			
Display method	·	Negative LCD (backlit LED) display 7-segment digital display (Character height: PV: 14.2 mm (green/red); SV: 4.9 mm (green)			
Main functions		Scaling function, 2-input calculation function, measurement operation selection, averaging, previous average value comparison, forced-zero, zero-limit, output hysteresis, output OFF delay, output test, teaching, display value selection, display color selection, key protection, bank selection, display refresh period, maximum/minimum hold, reset			
Ambient operating te	mperature	-10 to 55°C (with no icing or condensation)			
Ambient operating hu	umidity	25% to 85%			
Storage temperature		-25 to 65°C (with no icing or condensation)			
Altitude		2,000 m max.			
Accessories		Watertight packing, 2 fixtures, terminal cover, unit stickers, instruction manual. DeviceNet models also include a DeviceNet connector (Hirose HR31-5.08P-5SC(01)) and crimp terminals (Hirose HR31-SC-121) (See note 3.)			

Note: 1. DC power supply models require a control power supply capacity of approximately 1 A per Unit when power is turned ON. Particular attention is required when using two or more DC power supply models. The OMRON S8VS-series DC Power Supply Unit is recommended.

2. PNP input types are also available.

3. For K3HB-series DeviceNet models, use only the DeviceNet Connector included with the product. The crimp terminals provided are for Thin Cables.

## Characteristics

Display range		-19,999 to 99,999					
Sampling period		One input: 0.5 ms; Two inputs: 1.0 ms					
Comparative out- put response times (transistor	One input	OFF to ON: 1 ms max., ON to OFF: 1.5 ms max. (The time until the comparative output is output when there is a forced sudden change in the input signal from 15% to 95% or 95% to 15%.)					
outputs)	Two inputs	OFF to ON: 2 ms max., ON to OFF: 2.5 ms max. (The time until the comparative output is output when there is a forced sudden change in the input signal from 15% to 95% or 95% to 15%.)					
Linear output re- sponse time	One input	51 ms max. (The time until the final analog output is reached when there is a forced sudden change in the input signal from 15% to 95% or 95% to 15%.)					
	Two inputs	52 ms max. (The time until the final analog output is reached when there is a forced sudden change in the input signal from 15% to 95% or 95% to 15%.)					
Insulation resistar	nce	20 MΩ min. (at 500 VDC)					
Dielectric strength	ı	2,300 VAC for 1 min between external terminals and case					
Noise immunity		<ul> <li>100 to 240 VAC models: ±1,500 V at power supply terminals in normal or common mode (waveform with 1-ns rising edge and pulse width of 1 µs/100 ns)</li> <li>24 VAC/VDC models: ±1,500 V at power supply terminals in normal or common mode (waveform with 1-ns rising edge and pulse width of 1 µs/100 ns)</li> </ul>					
Vibration resistan	ce	Frequency: 10 to 55 Hz; Acceleration: 50 m/s <sup>2</sup> , 10 sweeps of 5 min each in X, Y, and Z directions					
Shock resistance		150 m/s <sup>2</sup> (100 m/s <sup>2</sup> for relay outputs) 3 times each in 3 axes, 6 directions					
Weight		Approx. 300 g (Base Unit only)					
Degree of protec-	Front panel	Conforms to NEMA 4X for indoor use (equivalent to IP66)					
tion	Rear case	IP20					
	Terminals	IP00 + finger protection (VDE0106/100)					
Memory protection	n	EEPROM (non-volatile memory) Number of rewrites: 100,000					
Applicable standa	rds	UL61010-1, CSA C22.2 No. 61010-1-04 EN61010-1 (IEC61010-1): Pollution degree 2/Overvoltage category II EN61326-1					
EMC		EMI: EN61326-1 Industrial electromagnetic environment Electromagnetic radiation interference CISPR 11 Group 1, Class A Terminal interference voltage CISPR 11 Group 1, Class A EMS: EN61326-1 Industrial electromagnetic environment Electrostatic Discharge Immunity EN61000-4-2: 4 kV (contact), 8 kV (in air) Radiated Electromagnetic Field Immunity EN61000-4-3: 10 V/m 1 kHz sine wave amplitude modulation (80 MHz to 1 GHz, 1.4 to 2 GHz) Electrical Fast Transient/Burst Immunity EN61000-4-4: 2 kV (power line), 1 kV (I/O signal line) Surge Immunity EN61000-4-5: 1 kV with line (power line), 2 kV with ground (power line) Conducted Disturbance Immunity EN61000-4-6: 3 V (0.15 to 80 MHz) Power Frequency Magnetic Immunity EN61000-4-8: 30 A/m (50 Hz) continuous time Voltage Dips and Interruptions Immunity EN61000-4-11: 0.5 cycle, 0°/180°, 100% (rated voltage)					

## ■ Input Ranges (Measurement Ranges and Accuracy)

Input	Input type	Measurement range	Indication range	Input impedance	Accuracy (at 23±5°C)	Maximum absolute rated input		
K3HB-SSD	0 to 20 mA	0.000 to 20.000 mA	-2.000 to 22.000 mA	120 $\Omega$ max.	One input:	±31 mA		
0	4 to 20 mA	4.000 to 20.000 mA	2.000 to 22.000 mA	-	±0.1% F.S.			
input	0 to 5 V	0.000 to 5.000 V	-0.500 to 5.500 mA	1 M $\Omega$ min.	<ul> <li>±1 digit max.</li> <li>Two inputs:</li> <li>±0.2% F.S.</li> </ul>	-	- +10 V	±10 V
1 to 5 V	1 to 5 V	1.000 to 5.000 V	0.500 to 5.500 V					
	±5 V	±5.000 V	±5.500 V	1	±1 digit max.			
	±10 V	±10.000 V	±11.000 V			±14.5 V		

Note: The accuracy is for an ambient temperature of  $23\pm5^{\circ}C$ .

I	nput type	DC curr	ent input		Input type		DC volta	ige input	
Connected	terminals	0-20	4-20	Connected	terminals	erminals 0-5 1-5 5		10	
Input A	In-F8	E2	- (E3)	Input A	In-F8		E4	-E3	
Input B	In-FP	E1 ·	- 🕄	Input B	In-tb		E5 -	- <b>E</b> 3	
DC current range (mA)	24.000	22.000	22.000	DC voltage range (V)					
Tange (IIIA)	20.000			Tallye (V)					11.000
	16.000			-	10.000	5.500	5.500	5.500	
	12.000			_	5.000	5.500	5.500	5.500	
	8.000			-	0.000	-0.500	0.500		
	4.000			_	-5.000	0.000	0.000	-5.500	
	0.000		2.000	_	-10.000			0.000	-11.000
	-4.000	-2.000							

The range shown in dark shading indicates the factory setting.

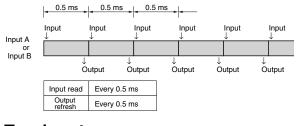
## Sampling and Comparative Output Response Times

The K3HB-S sampling and comparative output response times depend on the calculation methods, timing hold type, and, for simple averaging, the averaging times. Refer to the following description for details.

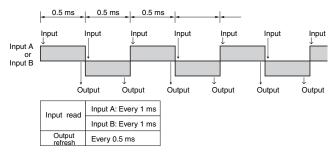
## Output Refresh Period

The K3HB-S repeats input reads, calculation, and judgement output processing. The output refresh period differs depending on whether there are one or two inputs, as outlined below.

## One Input



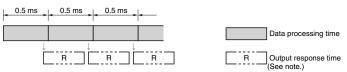
### Two inputs



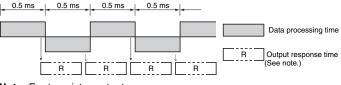
## ■ Output Response Time

The comparative output response time is the sum of the data processing time and the output (relay or transistor) response time.

## One Input



## Two Inputs



**Note:** For transistor outputs:

For one input: OFF to ON 1 ms and ON to OFF 1.5 ms For two inputs: OFF to ON 2 ms and ON to OFF 2.5 ms

For relay outputs: The relay operation time of 15 ms is added to the transistor output response times.

## ■ Event Input Ratings

Input type	S-TMR, HOLD, RESET, ZERO, BANK1, BANK2, BANK4	TIMING
Contact	ON: 1 k $\Omega$ max., OFF: 100 k $\Omega$ min.	
No-contact	OFF leakage current: 0.1 mA max. Load current: 4 mA max.	ON residual voltage: 3 V max. OFF leakage current: 1.5 mA max. Load current: 17 mA max. Maximum applied voltage: 30 VDC max.

## ■ Output Ratings

### Contact Output

Item	Resistive loads (250 VAC, cos∳=1; 30 VDC, L/R=0 ms)	Inductive loads (250 VAC, closed circuit, cos∳=0.4; 30 VDC, L/R=7 ms)
Rated load	5 A at 250 VAC 5 A at 30 VDC	1 A at 250 VAC 1 A at 30 VDC
Mechanical life expectancy	5,000,000 operations	
Electrical life expectancy	100,000 operations	

### Linear Output

Item	0 to 20 mA	4 to 20 mA	0 to 5 V	1 to 5 V	0 to 10 V	
Allowable load impedance	500 Ω max.	5 kΩ min.				
Resolution	Approx. 10,000					
Output error	±0.5%FS ±0.5%FS (1 V or less: no output for ±0.15 V; 0 V or less					

### **Serial Communications Output**

ltem	RS-232C, RS-485
Communications method	Half duplex
Synchronization method	Start-stop synchronization
Baud rate	9,600, 19,200, or 38,400 bps
Transmission code	ASCII
Data length	7 bits or 8 bits
Stop bit length	2 bits or 1 bit
Error detection	Vertical parity and FCS
Parity check	Odd, even

Note: For details on serial and DeviceNet communications, refer to the *Digital Indicator K3HB Communications User's Manual* (Cat.No. N129).

## Transistor Output

Maximum load voltage	24 VDC
Maximum load current	50 mA
Leakage current	100 μA max.

### BCD Output I/O Ratings (Input Signal Logic: Negative)

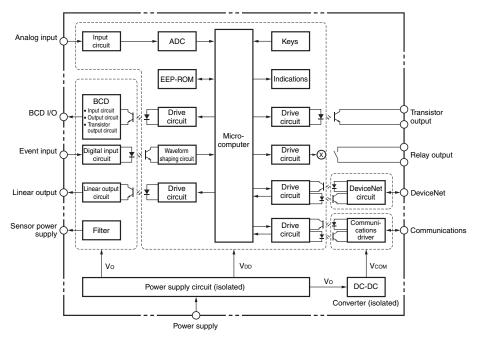
	I/O signal name		Item	Rating
Inputs	REQUEST HOLD	Input signal		No-voltage contact input
	MAX MIN RESET		urrent for age input	10 mA
		Signal level	ON voltage	1.5 V max.
			OFF volt- age	3 V min.
Outputs	DATA POLARITY OVER DATA VALID RUN	Maximum load voltage		24 VDC
		Maximum load current		10 mA
		Leakage current		100 μA max.
	HH H	Maximum load voltage		24 VDC
	PASS L	Maximum load current		50 mA
	LL	Leakag	e current	100 μA max.

Note: For details on serial and DeviceNet communications, refer to the *Digital Indicator K3HB Communications User's Manual* (Cat.No. N129).

## **DeviceNet Communications**

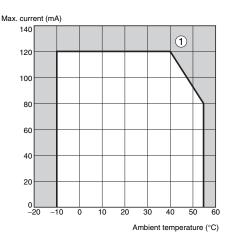
Communications prot	ocol	Co	onforms to DeviceNe	et				
Supported communi- cations	Remote I/O communications	Master-Slave connection (polling, bit-strobe, COS, cyclic) Conforms to DeviceNet communications standards.						
	I/O allocations	Al	locate any I/O data	using the Configurat	or.			
			locate any data, suc dicators.	h as DeviceNet-spec	ific parameters and	variable area for Digital		
		In	put area: 2 blocks, 6	60 words max.				
		0						
		(T	he first word in the a	rea is always allocate	ed for the Output Exe	ecution Enabled Flags.)		
	Message communications		plicit message com					
			ompoWay/F commu mmunications)	nications commands	s can be executed (ι	using explicit message		
Connection methods			ombination of multi-	drop and T-branch c	onnections (for trun	and drop lines)		
Baud rate			eviceNet: 500, 250,	or 125 Kbps (automa	atic follow-up)			
Communications media			Special 5-wire cable (2 signal lines, 2 power supply lines, 1 shield line)					
Communications dista	Communications distance							
			Baud rate	Network length (max.)	Drop line length (max.)	Total drop line length (max.)		
			500 Kbps	100 m (100 m)	6 m	39 m		
			250 Kbps	100 m (250 m)	6 m	78 m		
			125 Kbps	100 m (500 m)	6 m	156 m		
			The values in pare	ntheses are for Thic	k Cable.			
Communications pow	er supply	24-VDC DeviceNet power supply						
Allowable voltage fluc	tuation range	11 to 25-VDC DeviceNet power supply						
Current consumption			50 mA max. (24 VDC)					
Maximum number of nodes			64 (DeviceNet Configurator is counted as one node when connected)					
Maximum number of slaves			63					
Error control checks		CRC errors						
DeviceNet power supp	bly	Sı	upplied from Devicel	Net communications	connector			

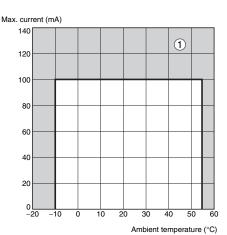
## Internal Block Diagram



### ■ Power Supply Derating Curve for Sensor (Reference Value) With 10 V

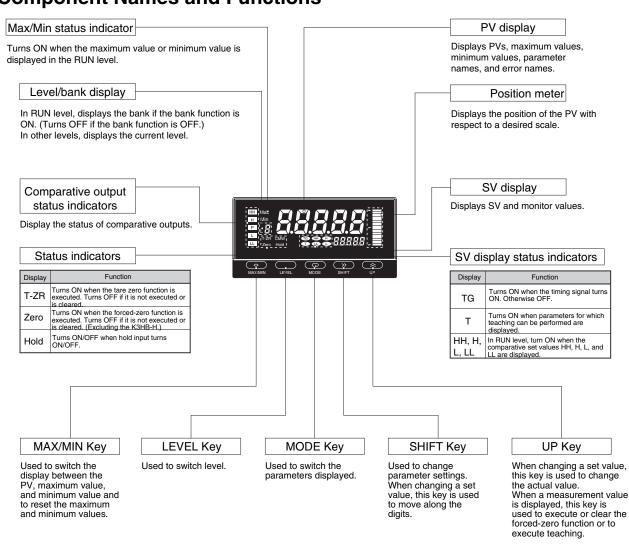
#### With 12 V





Note: 1. The above values are for standard mounting. The derating curve differs depending on the mounting conditions.

2. Do not use the Sensor outside of the derating area (i.e., do not use it in the area labeled A in the above graphics). Doing so may occasionally cause deterioration or damage to internal components.

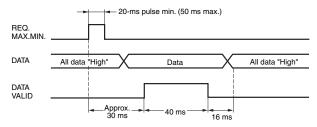


## Component Names and Functions

## BCD Output Timing Chart

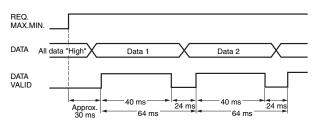
A REQUEST signal from a Programmable Controller or other external device is required to read BCD data.

### Single Sampling Data Output



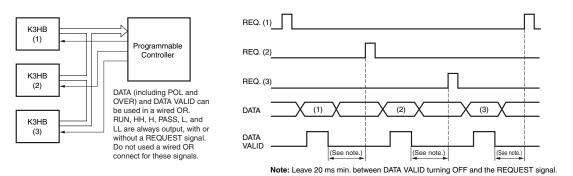
The data is set in approximately 30 ms from the rising edge of the REQUEST signal and the DATA VALID signal is output. When reading the data from a Programmable Controller, start reading the data when the DATA VALID signal turns ON. The DATA VALID signal will turn OFF 40 ms later, and the data will turn OFF 16 ms after that.

### **Continuous Data Output**



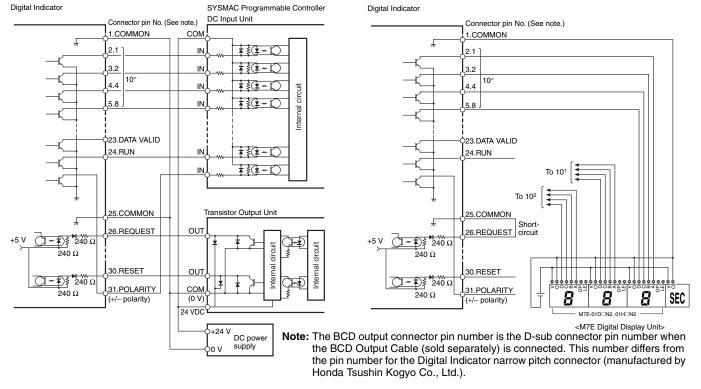
Measurement data is output every 64 ms while the REQUEST signal remains ON.

**Note:** If HOLD is executed when switching between data 1 and data 2, either data 1 or data 2 is output depending on the timing of the hold signal. The data will not go LOW.



### Programmable Controller Connection Example





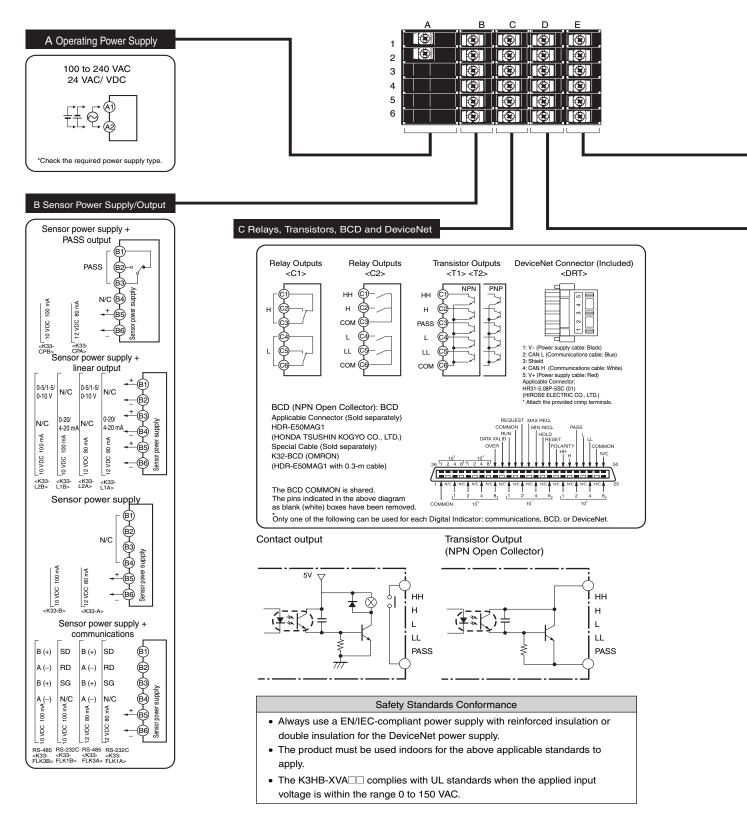
 Refer to the following User's Manual for application precautions and other information required when using the Digital Indicator: K3HB-S/-X/-V/-H Digital Indicator User's Manual (Cat. No. N128)
 The manual can be downloaded from the following site in PDF format: OMRON Industrial Web http://www.fa.omron.co.jp

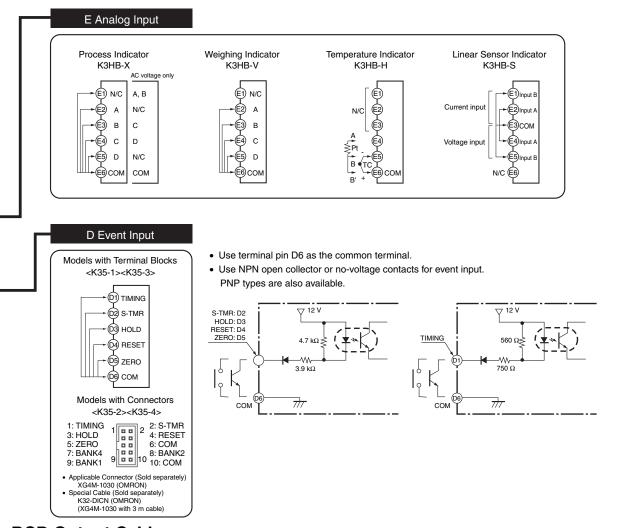
### OMRON

## ■ Connections

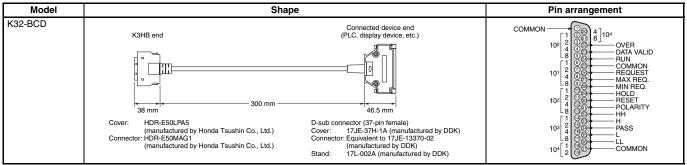
### **Terminal Arrangement**

Note: Insulation is used between signal input, event input, output, and power supply terminals.



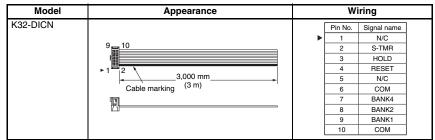


### **BCD Output Cable**



Note: The BCD Output Cable has a D-sub plug. Cover: 17JE-37H-1A (manufactured by DDK); Connector: equivalent to 17JE-23370-02 (D1) (manufactured by DDK)

### Special Cable (for Event Inputs with 8-pin Connector)



## Main Functions <u>Measurement</u>

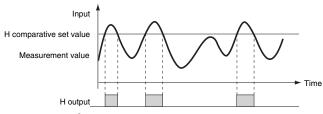
#### Input Calculation

- Two input circuits are provided. The input ranges for these circuits can be set independently. For example, one can be set to 4 to 20 mA and the other can be set to 1 to 5 V.
- In addition to calculations such as K (constant)–A (input for one circuit), it is possible to perform calculations based on the inputs for both circuits, such as A+B and A–B, making it possible to perform thickness measurement and level-difference measurement using displacement and length-measuring sensors.

#### **Timing Hold**

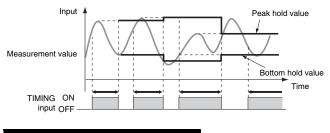
#### Normal

Continuously performs measurement and always outputs based on comparative results.



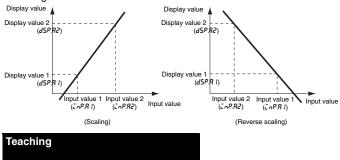
#### Peak Hold/Bottom Hold

• Measures the maximum (or minimum) value in a specified period.



#### Scaling

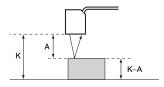
Scaling converts input signals in any way required before displaying them. The values can be manipulated by shifting, inverting, or +/– reversing.



Settings for scaling can be made using the present measurement values instead of inputting values with the SHIFT and UP Keys. This is a convenient function for making the settings while monitoring the operating status.

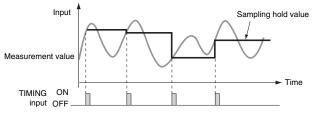
#### Standby Sequence

Turns the comparative output OFF until the measurement value enters the PASS range.



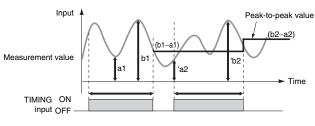
#### **Sampling Hold**

• Holds the measurement at the rising edge of the TIMING signal.



#### Peak-to-peak Hold

Measures the difference between the maximum and minimum values in a specified period.



#### Average Processing

Average processing of input signals with extreme changes or noise smooths out the display and makes control stable.

#### Previous Average Value Comparison

Slight changes can be removed from input signals to detect only extreme changes.

## Input Compensation/Display

#### Forced-zero

Forces the present value to 0. (Convenient for setting reference values or deducting tares for weight measurement.)

#### Tare Zero

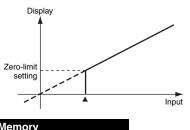
Shifts the current value measured with a forced zero to 0 again. It is possible to measure two or more compounds separately and then, by releasing the tare zero and forced-zero, measure the combined total.

#### Zero-trimming

Compensates for mild fluctuations in input signals due to factors such as sensor temperature drift, based on OK (PASS) data at measurement. (This function can be used with sampling hold, peak hold, or bottom hold.)

#### Zero-limit

Changes the display value to 0 for input values less than the set value. It is enabled in normal mode only. (This function can be used, for example, to stop negative values being displayed or to eliminate flickering and minor inconsistencies near 0.)



#### Interruption Memory

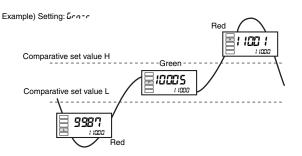
- The minimum and maximum values when the power supply is turned OFF can be saved if interruption memory is turned ON.
- If interruption memory is ON, the maximum and minimum values after the last resetting will be displayed.
- If interruption memory is OFF, the maximum and minimum values will be displayed after the power supply is turned ON (or after the reset input is performed).



The display refresh period can be lengthened to reduce flickering and thereby make the display easier to read.

#### **Display Color Selection**

Values can be displayed in either red or green. With comparative output models, the display color can also be set to change according to the status of comparative outputs (e.g., green to red or red to green).



#### **Display Value Selection**

The current display value can be selected from the present value, the maximum value, and the minimum value.

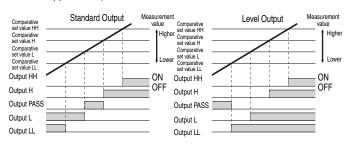
#### Step Value

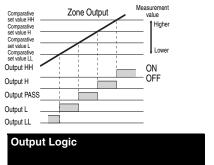
It is possible to specify (i.e., restrict) the values that the smallest displayed digit can change by. For example, if the setting is 2, the smallest digit will only take the values 0, 2, 4, 6, or 8 and if the setting is 5, it will only take the values 0 or 5. If the setting is 10, it will only take the value of 0.

## Output

#### **Comparative Output Pattern**

The output pattern for comparative outputs can be selected. In addition to high/low comparison with set values, output based on level changes is also possible. (Use the type of output pattern appropriate for the application.)



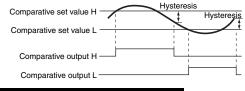


Reverses the output operation of comparative outputs for comparative results.

#### Hysteresis

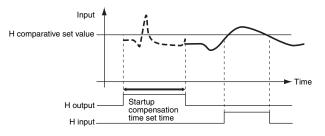
Prevents comparative output chattering when the measurement value fluctuates slightly near the set value.

#### Example: Comparative Output Pattern (Standard Output)



Startup Compensation Timer

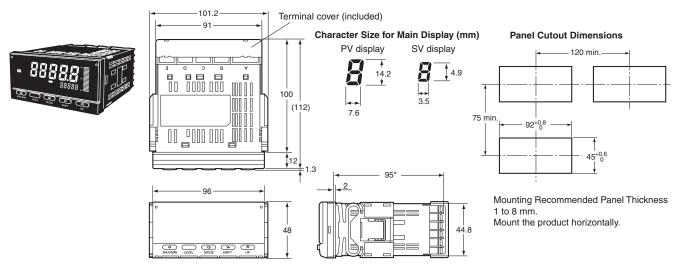
Measurement can be stopped for a set time using external input.



#### PASS Output Change

Comparative results other than PASS and error signals can be output from the PASS output terminal.

### Dimensions



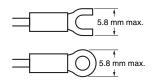
\*DeviceNet models: 97 mm Terminal: M3, Terminal Cover: Accessory

## Wiring Precautions

- For terminal blocks, use the crimp terminals suitable for M3 screws.
- Tighten the terminal screws to the recommended tightening torque of approx. 0.5 N·m.
- To prevent inductive noise, separate the wiring for signal lines from that for power lines.

## <u>Wiring</u>

• Use the crimp terminals suitable for M3 screws shown below.



## Unit Stickers

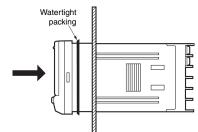
• Select the appropriate units from the unit sticker sheets provided and attach the sticker to the Indicator.

	<u>V</u>	ļ	Ā	X	A	%	J	Ра	Ω
	s	/	/	Ν	m	W	°C	m³	k
	°F g			min		mm		rpm	
	VA			mV		mA		Hz	
	m/min				OMRON				
	ουτ ουτ			υτ					

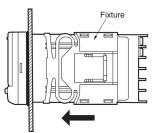
Note: When using for meters, such as weighing meters, use the units specified by regulations on weights and measures.

## Mounting Method

- 1. Insert the K3HB into the mounting cutout in the panel.
- 2. Insert watertight packing around the Unit to make the mounting watertight.

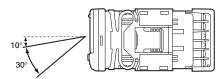


3. Insert the fixture into the grooves on the left and right sides of the rear case and push until it reaches the panel and is fixed in place.



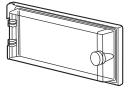
## ■ LCD Field of Vision

The K3HB is designed to have the best visibility at the angles shown in the following diagram.



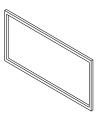
## Watertight Cover

Y92A-49N



## Rubber Packing

#### K32-P1



If the rubber packing is lost or damaged, it can be ordered using the following model number: K32-P1.

(Depending on the operating environment, deterioration, contraction, or hardening of the rubber packing may occur and so, in order to ensure the level of waterproofing specified in NEMA4, periodic replacement is recommended.)

Note: Rubber packing is provided with the Controller.

ALL DIMENSIONS SHOWN ARE IN MILLIMETERS.

To convert millimeters into inches, multiply by 0.03937. To convert grams into ounces, multiply by 0.03527.

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